

DUAL VECTOR SPACES, TRACES, AND CYCLICITY OF TRACE

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1. INTRODUCTION

This paper's purpose is to describe the dual of finite dimensional vector spaces V over an arbitrary field \mathbb{F} . Specifically, the aim is to show that V is finite dimensional, then construct a basis for it, and use this basis to define the trace of a linear map and show that it is independent of the basis chosen. The paper will conclude with a discussion of the cyclic property of traces.

2. DUAL SPACE OF A FINITE DIMENSIONAL VECTOR SPACE

Definition 2.1. Let V be a finite vector space over \mathbb{F} . The **dual space** of V is the vector space of all linear functionals on V such that $V^* = \mathcal{L}(V, \mathbb{F})$

Definition 2.2. If e_1, \dots, e_n is a basis of V , then the dual basis of e_1, \dots, e_n is the list f_1, \dots, f_n of elements of V^* , where each f_j is the linear functional on V such that $f_i(e_j) = 1$ if $j = i$ and $f_i(e_j) = 0$ otherwise.

Next, we'll see that f_1, \dots, f_n is also a basis for V^* . To see that f_1, \dots, f_n is linearly independent in V^* , we'll use the fact that only the i element is preserved when the linear map operates on the basis vector e_i , guaranteeing that all but the i terms will go to zero. And because $f_i(e_i) = 1$ for the i term, we are left with the scalar a_i . We'll then use our knowledge of dimensions of vector spaces and their relations to bases to show that f_1, \dots, f_n is a basis for V^*

Proposition 2.3. *The dual basis is a basis of the dual space $V^* = \mathcal{L}(V, \mathbb{F})$*

Proof. Suppose V is a finite dimensional vector space over \mathbb{F} and e_1, \dots, e_n is a basis in V . Let $a_1, \dots, a_n \in \mathbb{F}$ and define $f \in V^*$ as

$$f = a_1 f_1 + \dots + a_n f_n$$

and suppose

$$0 = a_1 f_1 + \dots + a_n f_n$$

By definition 2.2, $f_i(e_i) = (a_1 f_1 + \dots + a_n f_n)(e_i) = a_i f_i(e_i) = a_i$ for $i = 1, \dots, n$. Setting this to zero as above clearly yields $a_1 = \dots = a_n = 0$, thus showing f_1, \dots, f_n is linearly

independent in V^* . Also note that the dimension of the dual space V^* is equal to the dimension of the original vector space V , i.e. that $\dim(V^*) = \dim(V) = n$. Then f_1, \dots, f_n is a basis in V^* because every linearly independent list of vectors in V^* with length $\dim(V^*)$ is a basis of V^* . \square

3. TRACES

Proposition 3.1. *The trace of the linear map $A \in \mathcal{L}(V, V)$, defined as the trace of the matrix of A with respect to some basis e_1, \dots, e_n , is independent of the chosen basis*

Proof. Suppose V is a finite dimensional vector space over \mathbb{F} . Let e_1, \dots, e_n and e'_1, \dots, e'_n be bases for V and let f_1, \dots, f_n and f'_1, \dots, f'_n be their corresponding dual bases. Define Trace A as

$$\text{Tr } A = \sum_{j=1}^n f_j(Ae_j)$$

and note that $f_j(Ae_j)$ is the jj entry on the matrix of A and that the trace is the sum of the diagonal entries of the matrix associated with A and the basis e_1, \dots, e_n . Let

$$T = \mathcal{M}(I)$$

$$M = \mathcal{M}(Ae_j)$$

$$M' = \mathcal{M}(Ae'_j)$$

where I is the identity matrix with respect to bases e_1, \dots, e_n and e'_1, \dots, e'_n . If we let $M = T^{-1}M'T$ by the change of basis formula, then

$$\begin{aligned} \sum_{j=1}^n f_j(Ae_j) &= \text{Tr } A \\ &= \text{Tr } M \\ &= \text{Tr } T^{-1}M'T \\ &= \sum_{i,j,k} (T^{-1})_{ij} M'_{jk} T_{ki} \\ &= \sum_{i=1}^n \sum_{j,k} M'_{jk} (T_{ki} (T^{-1})_{ij}) \\ &= \sum_{j=1}^n \sum_{k=1}^n M'_{jk} (TT^{-1})_{kj} \end{aligned}$$

$$\begin{aligned}
&= \sum_{j=1}^n \sum_{k=1}^n M'_{jk} I_{kj} \\
&= \sum_{j=1}^n M'_{jj} \\
&= \text{Tr } M' \\
&= \sum_{j=1}^n f'_j(Ae'_j)
\end{aligned}$$

As desired. Hence, there is no need to specify a basis when discussing the trace of a linear operator or its associated matrix. \square

Example 3.2. Suppose $A \in \mathcal{L}(V, V)$ and let the list e_1, e_2, e_3 be a basis in V with f_1, f_2, f_3 as its corresponding dual basis. Show that $\text{Tr } A$ is equal to the sum of the diagonal entries on the matrix of A .

Let $Ae_j = \sum a_{jk}e_k$ be the matrix associated with A and the basis e_1, e_2, e_3 . Then

$$\begin{aligned}
\text{Tr } A &= \sum_{j=1}^3 f_j(Ae_j) \\
&= \begin{bmatrix} f_1, f_2, f_3 \end{bmatrix} \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \begin{bmatrix} e_1 \\ e_2 \\ e_3 \end{bmatrix} \\
&= \begin{bmatrix} f_1, f_2, f_3 \end{bmatrix} \begin{bmatrix} a_{11}e_1 + a_{12}e_2 + a_{13}e_3 \\ a_{21}e_1 + a_{22}e_2 + a_{23}e_3 \\ a_{31}e_1 + a_{32}e_2 + a_{33}e_3 \end{bmatrix} \\
&= f_1(a_{11}e_1 + a_{12}e_2 + a_{13}e_3) + f_2(a_{21}e_1 + a_{22}e_2 + a_{23}e_3) + f_3(a_{31}e_1 + a_{32}e_2 + a_{33}e_3) \\
&= f_1(a_{11}e_1) + 0 + 0 + 0 + f_2(a_{22}e_2) + 0 + 0 + 0 + f_3(a_{33}e_3) \\
&= a_{11}f_1e_1 + a_{22}f_2e_2 + a_{33}f_3e_3 \\
&= a_{11} + a_{22} + a_{33}
\end{aligned}$$

as desired.

The next result follows from 3.1 and greatly simplifies our definition of trace. Because all of the non- jj entries on the matrix associated with A go to zero, the next definition says that, given any square matrix, we can ignore all but the jj entries and simply take the sum of the main diagonal without referring to any basis.

Definition 3.3. Given any square matrix A , the **trace** of A is the sum of the entries on the main diagonal. i.e.

$$\operatorname{Tr} A = \sum_{j=1}^n a_{jj} = a_{11} + a_{22} + \dots + a_{nn}$$

where a_{jj} denotes the entry on the j th row and j th column of A .

Example 3.4. Given an $n \times n$ identity matrix I , show that $\operatorname{Tr} I = n$ when $n = 3$. I.e., show that the diagonals of the 3×3 identity matrix add up to n .

$$\begin{aligned} \operatorname{Tr} I &= \sum_{j=1}^3 i_{jj} \\ &= 1 + 1 + 1 \\ &= 3 \end{aligned}$$

which is equal to n as desired.

Example 3.5. Let $A = \begin{bmatrix} 6 & 13 & 2 \\ 2 & 1 & 0 \\ 4 & 9 & 3 \end{bmatrix}$ and define $\operatorname{Tr} A = \sum_{j=1}^n a_{jj}$. Then

$$\begin{aligned} \operatorname{Tr} A &= \sum_{j=1}^3 a_{jj} \\ &= 6 + 1 + 3 \\ &= 10 \end{aligned}$$

Next we will prove the cyclicity of trace using the definition of matrix multiplication.

Proposition 3.6. The property that $\operatorname{Tr}(AB) = \operatorname{Tr}(BA)$ for all $A, B \in \mathcal{L}(V, V)$ is called the cyclicity of trace.

$$\begin{aligned} \operatorname{Tr}(AB) &= \sum_{i=1}^n (AB)_{ii} \\ &= \sum_{i=1}^n \sum_{j=1}^n a_{ij} b_{ji} \\ &= \sum_{j=1}^n \sum_{i=1}^n b_{ij} a_{ij} \\ &= \sum_{j=1}^n (BA)_{jj} \\ &= \operatorname{Tr}(BA) \end{aligned}$$